	·			
L Number	Hits		DB .	Time stamp
1	15	,	USPAT;	2003/09/11 10:23
		(drive near2 controller) and (vehicle same	EPO; JPO;	1 .
		motion same controller)	DERWENT;	
			IBM TDB	
3	29	(electric\$4 same brake) and (drive near2	USPĀT;	2003/09/11 11:24
		controller) and (vehicle same motion same	EPO; JPO;	
		controller) and CAN .	DERWENT;	
		conclosive, and can	IBM TDB	}
	20	(electric\$4 same brake) and (drive near2	USPAT;	2003/09/11 10:46
4	29	controller) and (vehicle same motion same		2003/03/11 10.40
			EPO; JPO;	1
	2	controller) and (CAN or (control near3 area	DERWENT;	
	_	near3 network))	IBM_TDB	
· 5	0	(USPAT;	2003/09/11 10:52
		controller) and (motion near3 controller) and	EPO; JPO;	
		(radio near3 communication)	DERWENT;	
			IBM_TDB	
6	3	(electric\$4 same brak\$4) and (drive same	USPAT;	2003/09/11 10:57
		controller) and (motion same controller) and	EPO; JPO;	
-	İ	(radio near3 communication)	DERWENT;	
		(Tadio iidais communication)	IBM TDB	
7	1	(electric\$4 same brak\$4) and (drive same	USPAT:	2003/09/11 10:58
['		controller) and (motion same controller) and	EPO; JPO;	2003/09/11 10:56
	!			
		(bidirect\$5 same multiplex same	DERWENT;	
		communication)	IBM_TDB	
8	10	(electric\$4 same brak\$4) and (drive same	USPAT;	2003/09/11 11:04
		controller) and (motion same controller) and	EPO; JPO;	
		(bidirect\$5 same communication)	DERWENT;	
			IBM_TDB	
9	33	(electric\$4 same brak\$4) and (drive same	USPAT;	2003/09/11 13:31
		controller) and (motion same controller) and	EPO; JPO;	
		(signal near3 line) and (power near3 line)	DERWENT;	
		(0-3	IBM TDB	
10	8	(electric\$4 same brak\$4) and (signal near3	USPAT;	2003/09/11 11:18
10	·	line)and (power near3 line)and (cable same		2003/03/11 11:18
		sheath)	EPO; JPO;	
. 0		sneath)	DERWENT;	
		(3 , 1 %, 1 3 %, 3 , () 3	IBM_TDB	
11 .	0	(electric\$4 same brak\$4) and ((signal near3	USPAT;	2003/09/11 11:20
		line)same (coaxial near3 wire))and ((power	EPO; JPO;	
		near3 line)same (twisted near3 wire))	DERWENT;	
			IBM_TDB	
12	2		USPAT;	2003/09/11 11:21
1		wire)and (twisted near3 wire)	EPO; JPO;	
			DERWENT;	
			IBM TDB	
13	17	(electric\$4 same brak\$4) and (coaxial same	USPAT;	2003/09/11 11:22
[i		wire) and (twisted same wire)	EPO; JPO;	. , =======
			DERWENT;	·
			IBM TDB	
14	3	(electric\$4 same brake) and (pad near3	USPAT;	2003/09/11 11:25
		abrasion near3 sensor)	EPO; JPO;	
			DERWENT;	
			IBM TDB	
15	6	(elegtrick) game broke) and (2003/00/11 11 05
123	ا	(electric\$4 same brake) and (pad same	USPAT;	2003/09/11 11:27
		abrasion same sensor)	EPO; JPO;	·
			DERWENT;	
			IBM_TDB	l — , — , — l
16	101	(electric\$4 same brake) and (air near2	USPAT;	2003/09/11 11:29
		pressure near2 sensor)	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
17	31	(electric\$4 near3 brake) and (air near2	USPAT;	2003/09/11 13:02
	İ	pressure near2 sensor)	EPO; JPO;	, , = =
			DERWENT;	
			IBM TDB	
18	1	(electric\$4 near3 brake) and (drive near3	USPAT;	2003/09/11 13:04
	-	controller) and (vehicle near3 motion near3	EPO; JPO;	~~~~
		controller)	DERWENT;	
		CONCLOSIES		
			IBM_TDB	

			<i>y</i> .	
19	9	(electric\$4 same brak\$4) and (drive near3	USPAT;	2003/09/11 13:38
	1	controller) and (vehicle near3 motion near3	EPO; JPO;	
-		controller)	DERWENT;	
			IBM_TDB	
20	770	1 .	USPAT	2003/09/11 13:38
21	6860		USPAT	2003/09/11 13:40
		brake		/ /
22	19503	(signal near3 line) and (power near3 line)	USPAT	2003/09/11 13:41
23	126	1 '	USPAT	2003/09/11 13:41
		brake) and ((signal near3 line) and (power		
24	7	near3 line)) 701/70.ccls. and ((electronic near3	USPAT	2003/09/11 14:06
24	/	brake)or(electric\$5 near3 brake) and	USFAI	2003/03/11 14:08
		((signal near3 line)and (power near3 line)))		
26	413	(drive near3 controller) and (motion near3	USPAT	2003/09/11 14:07
20	113	controller)	001111	2003, 03, 12 21.0,
27	73	(drive near3 controller) and (motion near3	USPAT	2003/09/11 14:08
-		controller) and (signal near3 line)		
28	28	(drive near3 controller) and (motion near3	USPAT	2003/09/11 14:08
		controller) and (signal near3 line) and brak\$4		
25	158	701/70.ccls. and (electronic near3	USPAT	2003/09/11 14:15
	1	brake)or(electric\$5 near3 brake)		
29	0	(wheel near3 speed near3 sensor)and (pad	USPAT	2003/09/11 14:16
		near3 abrasion near3 sensor)		
30	3104	_	USPAT	2003/09/11 14:17
31	7210	wheel near3 speed near3 sensor	USPAT;	2003/09/11 14:17
			EPO; JPO;	
			DERWENT;	
22			IBM_TDB	0003/00/11 14 10
33	11	pad near3 abrasion near3 sensor	USPAT;	2003/09/11 14:18
			EPO; JPO; DERWENT;	
			IBM TDB	
34	0	(electronic near3 brake)or(electric\$5 near3	USPAT;	2003/09/11 14:18
"		brake) and (pad near3 abrasion near3 sensor)	EPO; JPO;	2003, 03, 12 21.20
			DERWENT;	
			IBM TDB	
35	0	701/70.ccls. and (pad near3 abrasion near3	USPAT;	2003/09/11 14:18
		sensor)	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
36	60	pad same abrasion same sensor	USPAT;	2003/09/11 14:18
8			EPO; JPO;	
			DERWENT;	
37		/oleahmania maawa hwales\(-1	IBM_TDB	0000/00/11 14 10
37	2	(electronic near3 brake) or (electric\$5 near3	USPAT;	2003/09/11 14:19
		brake) and (pad same abrasion same sensor)	EPO; JPO;	
			DERWENT;	
38	6989	air near3 pressure near3 sensor	USPAT;	2003/09/11 14:19
	0,00	arr means proporte means beinger	EPO; JPO;	2003,03,11 14.19
			DERWENT;	
			IBM TDB	
39	62	(electronic near3 brake)or(electric\$5 near3	USPAT;	2003/09/11 14:20
		brake) and (air near3 pressure near3 sensor)	EPO; JPO;	
		-	DERWENT;	
			IBM_TDB	
32	44	(701/70.ccls. and (electronic near3	USPAT;	2003/09/11 14:31
		brake)or(electric\$5 near3 brake)) and (wheel	EPO; JPO;	
		near3 speed near3 sensor)	DERWENT;	
			IBM_TDB	

Number Hits Search Text 15 15 15 15 15 15 15 1					
	L Number	Hits		DB	Time stamp
motion same controller) DERMENT; BM TDB Controller) and (vehicle same motion same controller) SPAT; Controller) and (vehicle same motion same controller) Co	1	15			2003/09/11 10:23
1		1	(drive near2 controller) and (vehicle same	EPO; JPO;	
29			motion same controller)	DERWENT;	
Controller) and (vehicle same motion same EFO; JPO; Controller) and (CAN CONTROL CONTR				IBM_TDB	
Controller) and (vehicle same motion same controller) and CAN	3	29	(electric\$4 same brake) and (drive near2	USPAT;	2003/09/11 11:24
Controller) and CAN	ļ			EPO; JPO;	
1			controller) and CAN		
1				1	
Controller)and (vehicle same motion same controller)and (CAN or (control near3 area near3 network))	4	29	(electric\$4 same brake) and (drive near2		2003/09/11 10:46
Controller)and (CAN or (control near3 area near3 network) (electric\$4 same brake) and (drive near2 controller)and (motion near3 controller) and (radio near3 communication) (electric\$4 same brak\$4) and (drive same controller) and (radio near3 communication) (electric\$4 same brak\$4) and (drive same controller) and (bidirect\$5 same multiplex same controller) and (bidirect\$5 same multiplex same controller) and (bidirect\$5 same communication) (electric\$4 same brak\$4) and (drive same controller) and (bidirect\$5 same communication) (electric\$4 same brak\$4) and (drive same controller) and (signal near3 line) and (power near3 line) and (signal near3 line) and (power near3 line) and (signal near3 line) same (coaxial near3 wire)) (electric\$4 same brak\$4) and (signal near3 line) same (coaxial near3 wire)) (electric\$4 same brak\$4) and (signal near3 line) same (coaxial near3 wire)) (electric\$4 same brak\$4) and (signal near3 line) same (coaxial near3 wire)) (electric\$4 same brak\$4) and (signal near3 line) same (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) and (coaxial near3 wire)) (electric\$4 same brak\$4) (electric\$4 same brak\$4) (electric\$4 same brak\$4) (electric\$4 same brak\$6) (electric\$4 same brak\$6) (electric\$6 same brak\$6) (electric\$6 same brak\$6) (electric\$6 same brak\$6) (electric\$6 same brak\$6) (electric\$6 same brak\$6) (electric\$6 same brak\$6) (electric\$6 same brak\$6) (electric\$6 same brak\$6)	-				
near3 network) 0 (electric44 same brake) and (drive near2 controller) and (motion near3 controller) and (radio near3 communication) Sept. JPO; JPO; DERNEMT; Cadio near3 communication) 1 (electric44 same brak44) and (drive same controller) and (bidirect55 same multiplex same controller) and (bidirect55 same brak54) and (drive same controller) and (bidirect55 same brak54) and (drive same controller) and (bidirect55 same controller) and (bidirect55 same controller) and (bidirect55 same controller) and (bidirect55 same controller) and (signal near3 line) and (power near3 line) and (
Celectric\$4 same brake) and (drive near2 controller) and (notion near3 controller) and (near3 communication) Celectric\$4 same brak\$4\) and (drive same controller) and (bidirect\$5 same multiplex same controller) and (notion same controller) and (notion same controller) and (notion same controller) and (notion same controller) and (notion same controller) and (signal near3 line) and (power near3 line) and (power near3 line) and (notion same controller) and (signal near3 line) and (power near3 line) and (notion same controller) and (notion same sont) (notion sam	†		l · · · · · · · · · · · · · · · · · · ·		
Controller) and (motion near3 controller) and (radio near3 communication)	5	0	1	USPAT:	2003/09/11 10:52
Cradio near3 communication DERMENT; IRM TDB 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:57 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 10:58 2003/09/11 11:04 2			1		
1	i				
			(Tadio nears communication)	•	
Controller)and (motion same controller) and (radio near3 communication) Celectric\$4 same brak\$4) and (drive same communication) Celectric\$5 same brak\$4) and (drive same communication) Celectric\$4 same brak\$4) and (drive same communication) Celectric\$4 same brak\$4) and (drive same controller) and (bidirect\$5 same communication) Celectric\$4 same brak\$4) and (drive same controller) and (bidirect\$5 same communication) Celectric\$4 same brak\$4) and (drive same controller) and (signal near3 line) and (power near3 line) Celectric\$4 same brak\$4) and (signal near3 line) Celectric\$4 same brak\$4) and (signal near3 line) Celectric\$4 same brak\$4) and (signal near3 line) Celectric\$4 same brak\$4) Celectric\$4 same brak\$4] Celectric	6	2	(electric\$4 same brak\$4) and (drive same		2003/09/11 10:57
(radio near3 communication) DERMENT; IBM TDB USPAT; 2003/09/11 10:58 2003/09/11 11:04 2003/09/	8				2003/03/11 10.3/
1					
1	1		(radio hears communication)	1	
Controller) and (motion same controller) and (bidirect\$5 same multiplex same controller) and (electric\$4 same brak\$4) and (drive same controller) and (bidirect\$5 same communication) Controller and (motion same controller) and (bidirect\$5 same communication) DERWENT; IBM TDB USPAT; EPO; JPO; DERWENT; IBM T	1 -		(oleganist) and (drive acre		2002/09/11 10:50
DERWENT; Same multiplex same Communication Communication Communication Communication Communication Controller) and (motion same controller) and (bidirect\(\frac{5}{5}\) same communication DERWENT; EPO; JPO;	'	1		1	\\ \^003\03\II I0:28 \\
Communication Clectric\$4 same brak\$4 and (drive same controller) and (bidirect\$5 same communication) EPO; JPO; DERWENT; EPO;					
8 10 (electric\$4 same brak\$4) and (drive same controller) and (bidirect\$5 same communication) DERWENT; IBM TDB USPĀT; EPO; JPO; DE					
Controller)and (motion same controller)and (bidirect\$5 same communication)	ļ _		l ·		
(bidirect\$5 same communication)	8	10		•	2003/09/11 11:04
9 33 (electric\$4 same brak\$4) and (drive same controller) and (signal near3 line) and (power near3 line) 10 8 (electric\$4 same brak\$4) and (signal near3 line) and (power near3 line) and (power near3 line) 11 0 (electric\$4 same brak\$4) and (signal near3 line) and (power near3 line) and (power near3 line) and (power near3 line) and (power near3 line) and (signal near3 line) and (power near3 line) and (signal near3 line) and (lelectric\$4 same brak\$4) and (signal near3 line) same (coaxial near3 wire)) 12 2 (electric\$4 same brak\$4) and (coaxial near3 wire)) 13 17 (electric\$4 same brak\$4) and (coaxial same wire) and (twisted near3 wire) 14 3 (electric\$4 same brak\$4) and (coaxial same wire) and (twisted same wire) 15 (electric\$4 same brak\$4) and (pad near3 abrasion near3 sensor) 16 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 17 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 18 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 19 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 10 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 10 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 11 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 12 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 13 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 14 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 15 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 16 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 17 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 18 (electric\$4 same brak\$6) and (pad near3 abrasion same sensor) 19 (electric\$4 same brak\$6) and (pad near3 abrasion same sensor) 10 (electric\$4 same brak\$6) and (pad near3 abrasion same sensor) 10 (electric\$5 same brak\$6 and (pad near3 abrasion same sensor) 10 (electric\$6 same brak\$6 and (pad near3 abrasion same sensor) 10 (electric\$7 same brak\$7 same brak\$8 same sensor) 11 (electric\$8 sa	1				
9 33 (electric\$4 same brak\$4) and (drive same controller) and (signal near3 line) and (power near3 line) and (cable same sheath) 10 8 (electric\$4 same brak\$4) and (signal near3 line) and (power near3 line) and (cable same sheath) 11 0 (electric\$4 same brak\$4) and (signal near3 line) same (coaxial near3 wire)) and (signal near3 line) same (twisted near3 wire)) 12 2 (electric\$4 same brak\$4) and (coaxial near3 wire) and (twisted near3 wire) 13 17 (electric\$4 same brak\$4) and (coaxial same wire) abrasion near3 sensor) 14 3 (electric\$4 same brak\$4) and (coaxial same wire) abrasion near3 sensor) 15 6 (electric\$4 same brak\$4) and (pad near3 abrasion same sensor) 16 101 (electric\$4 same brak\$4) and (pad same abrasion same sensor) 17 31 (electric\$4 same brak\$4) and (air near2 pressure near2 sensor) 18 19 (electric\$4 same brak\$4) and (pad same sensor) 19 (electric\$4 same brak\$4) and (pad same sensor) 10 (electric\$4 same brak\$4) and (pad same sensor) 11 20 (electric\$4 same brak\$4) and (pad same sensor) 12 (electric\$4 same brak\$4) and (pad same sensor) 13 (electric\$4 same brak\$4) and (pad same sensor) 14 3 (electric\$4 same brak\$4) and (pad same sensor) 15 6 (electric\$4 same brak\$4) and (pad same sensor) 16 101 (electric\$4 same brak\$4) and (pad same sensor) 17 (electric\$4 same brak\$4) and (pad same sensor) 18 (electric\$4 same brak\$4) and (pad same sensor) 19 (electric\$5 (electric\$4 same brak\$4) and (pad same sensor) 10 (electric\$5 (e]		(bidirect\$5 same communication)		
Controller) and (motion same controller) and (signal near3 line) and (power near3 line) DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IIBM_TDB USPAT; EPO; JPO; DERWENT; IIBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT;				_	
(signal near3 line) and (power near3 line) DERWENT; IBM_TDB 1	9	33			2003/09/11 11:14
TBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; EPO; JPO; DE	[
10	1		(signal near3 line) and (power near3 line)	•	
line) and (power near3 line) and (cable same sheath) Sheath) Cable same EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; EPO; JPO; DER					
Sheath DERMENT; IBM_TDB USPAT; EPO; JPO; DERWENT; EPO; JPO	10	8			2003/09/11 11:18
11				1	
11 0 (electric\$4 same brak\$4) and ((signal near3 line)same (coaxial near3 wire)) and ((power near3 line)same (twisted near3 wire)) 12 2 (electric\$4 same brak\$4) and (coaxial near3 wire)	İ		sheath)		
line)same (coaxial near3 wire))and ((power near3 line)same (twisted near3 wire)) EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT	ł			_	
near3 line)same (twisted near3 wire) DERWENT; IBM TDB USPAT; EPO; JPO; DERWENT; IBM TDB USPAT;	11	0		I	2003/09/11 11:20
12 2 (electric\$4 same brak\$4) and (coaxial near3 wire) IBM_TDB USPAT; EPO; JPO; DERWENT; E				EPO; JPO;	
12 2 (electric\$4 same brak\$4) and (coaxial near3 USPĀT; EPO; JPO; DERWENT; IBM_TDB USPĀT; IBM_TDB		i	near3 line)same (twisted near3 wire))		
wire) and (twisted near3 wire) 17 (electric\$4 same brak\$4) and (coaxial same WISPAT; IBM_TDB]			IBM_TDB	
DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; EPO;	12	2			2003/09/11 11:21
13 17 (electric\$4 same brak\$4) and (coaxial same wire) 18M_TDB USPAT; EPO; JPO; DERWENT; EPO; JP			wire)and (twisted near3 wire)	EPO; JPO;	
17 (electric\$4 same brak\$4) and (coaxial same wire) USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT;		1		DERWENT;	
wire) and (twisted same wire)					
DERWENT; IBM_TDB USPAT; abrasion near3 sensor) 6 (electric\$4 same brake) and (pad near3 abrasion same sensor) 6 (electric\$4 same brake) and (pad same abrasion same sensor) 15 (electric\$4 same brake) and (pad same abrasion same sensor) 16 101 (electric\$4 same brake) and (air near2 pressure near2 sensor) 17 31 (electric\$4 near3 brake) and (air near2 pressure near2 sensor) DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; EPO; JPO; DERWENT; PROSSURE NEARS DERWENT; DERWENT; DERWENT;	13	17			2003/09/11 11:22
14 3 (electric\$4 same brake) and (pad near3 USPAT; EPO; JPO; DERWENT; IBM_TDB 15 6 (electric\$4 same brake) and (pad same abrasion same sensor) 16 101 (electric\$4 same brake) and (air near2 pressure near2 sensor) 17 31 (electric\$4 near3 brake) and (air near2 pressure near2 sensor) 18			wire)and (twisted same wire)		
14 3 (electric\$4 same brake) and (pad near3 USPĀT; EPO; JPO; DERWENT; IBM_TDB 15 (electric\$4 same brake) and (pad same abrasion same sensor) EPO; JPO; DERWENT; IBM_TDB USPĀT; EPO; JPO; DERWENT; IBM_TDB USPĀT; EPO; JPO; DERWENT; IBM_TDB USPĀT; EPO; JPO; DERWENT; IBM_TDB USPĀT; EPO; JPO; DERWENT; IBM_TDB USPĀT; EPO; JPO; DERWENT; IBM_TDB USPĀT; EPO; JPO; DERWENT; IBM_TDB USPĀT; EPO; JPO; DERWENT; EPO; JPO; DERWENT; EPO; JPO; DERWENT;	i			1	
abrasion near3 sensor) 6 (electric\$4 same brake) and (pad same USPAT; EPO; JPO; DERWENT; abrasion same sensor) 16 101 (electric\$4 same brake) and (air near2 USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; Pressure near2 sensor) 17 31 (electric\$4 near3 brake) and (air near2 USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; PRESSURE near2 sensor) 18 (electric\$4 near3 brake) and (air near2 USPAT; EPO; JPO; DERWENT;				_	
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15 (electric\$4 same brake) and (pad same abrasion same sensor) 16 (electric\$4 same brake) and (air near2 pressure near2 sensor) 17 (electric\$4 near3 brake) and (air near2 pressure near2 sensor) 18 (electric\$4 near3 brake) and (air near2 pressure near2 sensor) 18 (electric\$4 near3 brake) and (air near2 pressure near2 sensor) 18 (electric\$4 near3 brake) and (air near2 pressure near2 sensor) 18 (electric\$4 same brake) and (air near2 pressure near2 sensor) 18 (electric\$4 same brake) and (air near2 pressure near2 sensor) 18 (electric\$4 same brake) and (air near2 pressure near2 sensor)			abrasion near3 sensor)	EPO; JPO;	
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16 101 (electric\$4 same brake) and (air near2 USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; IBM_TDB USPAT; EPO; JPO; DERWENT; pressure near2 sensor) EPO; JPO; DERWENT;				IBM TDB	
pressure near2 sensor) EPO; JPO; DERWENT; IBM_TDB USPAT; pressure near2 sensor) Pressure near2 sensor) EPO; JPO; DERWENT; DERWENT;	16	101	(electric\$4 same brake) and (air near2		2003/09/11 11:29
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